Kriging Demy What's going on under the ho Lachlan Astfalck

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Stified od of our favourite interpolator?



What is it, why do we care?

If you've asked SPSS or GIS to interpolate something before it's probably using Kriging or something related.



- Kriging is one of the most influential interpolation methods in statistics, geosciences, engineering, and anything else that needs interpolation.

The multiple regression procedure for arriving at the **best linear unbiased** [predictor] or best linear weighted moving average [predictor] of the ore grade of an ore block (of any size) by assigning an optimum set of weights to all the available and relevant data inside and outside the ore block





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Georges Matheron

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"Everything is related to everything else, but near things are more related than distant things" - Tobler's First Law of Geography



Building up interpolation



Building up interpolation



Building up interpolation



Tobler's First Law



It is more desirable to predict from points closer rather than points further away

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Sensible interpolation methods include...

- Regression methods
- **Bi-linear interpolation**
- Inverse distance weighting
- Nearest neighbour predictions
- Spline interpolation
- Kriging

be thought of as realisations from a latent stochastic process.

Denote by s_i the spatial locations and $Z(s_i)$ the observed data that may

be thought of as realisations from a latent stochastic process.

Denote the covariance between any two points as $cov(Z(s), Z(s')) \equiv$ C(s, s').

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- We are going to focus on predicting the stochastic process, $Z(s_0)$, at a single location, s_0 .
- We're going to assume all data have point support.

a weighted linear average of the observed data that minimises the mean-squared error



We want the **best linear unbiased predictor** of $Z(s_0)$. This is given by

 $\mathbb{E}\left(\left(Z(s_0) - \sum_{i=1}^n a_i Z(s_i) - k\right)^2\right)$

Cranking out the math Minimising this objective yields $\mathbf{a} = \mathbf{c}'C^{-1} \qquad k = E\left(Z(s_0)\right) + \mathbf{c}'C^{-1}E(\mathbf{Z})$ where $\mathbf{c} \equiv (C(s_0, s_1), \dots, C(s_0, s_n))'$ and $C_{i,j} \equiv C(s_i, s_j)$.

(we're about to go through why...)

We may thus say that the optimal predictor of $Z(s_0)$ is

$$Z^*(s_0) = E\left(Z(s_0)\right)$$

with prediction error

$s_0) + c'C(Z - E(Z))$

$E\left(\left(Z(s_0) - Z^*(s_0)\right)^2\right) = C(s_0, s_0) - c'C^{-1}c$

First we need some basic identities:

$$E\left(x^2\right) = \mathbf{v}$$

- $ar(x) + (E(x))^{2}$
- var(x + y) = var(x) + 2cov(x, y) + var(y)
 - cov(ax, y) = acov(x, y)
 - $var(ax) = a^2 var(x)$
 - $\operatorname{var}(x + c) = \operatorname{var}(x)$

 $E\left(\left(Z(s_0) - \mathbf{a}^T \mathbf{Z} - k\right)^2\right) = \operatorname{var}\left(Z(s_0) - \mathbf{a}^T \mathbf{Z}\right) + \left(E\left(Z(s_0) - \mathbf{a}^T \mathbf{Z} - k\right)\right)^2$

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and so $k = E(Z(s_0)) - a^T E(Z)$

$$\begin{split} \mathcal{I}(s_0) &- \mathbf{a}^T \mathbf{Z} \right) + \left(E \left(Z(s_0) - \mathbf{a}^T \mathbf{Z} - k \right) \right)^2 \\ \text{so that} \left(E \left(Z(s_0) - \mathbf{a}^T \mathbf{Z} - k \right) \right)^2 = 0. \end{split}$$

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$$)$$
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$$-2\operatorname{cov}\left(Z(s_0), Z\right) + 2a^T \operatorname{var}(Z) = 0$$

and so $a^T = \operatorname{cov}\left(Z(s_0), Z\right) \operatorname{var}(Z)^{-1}$

В

Differentiating with respect to a:

But how do we figure out covariance?

WELGOME TO STATISTICS



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Recall that this squared distance is very reminiscent of the definition of variance: $var[x] = E((x - E[x])^2)$.



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The covariance function describes how two points co-vary as a function of distance

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The covariance function $C\left(d(s_i, s_j)\right)$ Nugget Partial Sill







Once we have a fit semivariogram or covariance function we're good to go

$\hat{\gamma}(h) = \frac{1}{n_h} \sum_{\substack{s_i, s_k \in N(h)}} \sum_{k \in N(h)} \sum_{h \in N(h)} \sum_{k \in N(h)} \sum_{h \in N(h)} \sum_{k \in N(h)} \sum_{h \in N(h)} \sum_{h \in N(h)} \sum_{k \in N(h)}$

for some choice of $h = |s_i - s_k|$

$$\left(Z\left(s_{i}\right) - Z\left(s_{k}\right)\right)^{2}$$







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Be aware of what covariance function is being assumed - different functions yield drastically different interpolations.

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 $E\left(Z^*(s)\right)$

 $\operatorname{var}\left(Z^{*}(s)\right)$



A rose by any other name...

Simple Kriging

Ordinary Kriging

Universal Kriging

Disjunctive Kriging

Linear Regression

Gaussian Processes

Kalman Filtering

Gaussian Markov Random Fields

Wiener-Kolmogorov Predictions

Spline Regression in Reproducing Kernel Hilbert Spaces

Bayes linear analysis

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The essence/ideas underpinning kriging are everywhere! If you're ever interpolating or regressing, be mindful of where it may be.

What we haven't talked about

Stationarity, types of covariance functions and positive definiteness

Methods of inference

- Kriging with big data
- Assumptions of Gaussinity



DIDN'T HAVE ENOUGH MATH."

CONFIDENCE INTERVAL

"LISTEN, SCIENCE IS HARD. BUT I'M A SERIOUS PERSON DOING MY BEST.*



"I HAD AN IDEA FOR HOW TO CLEAN UP THE DATA. WHAT DO YOU THINK?"





EXTEND IT AAAAAA!!"

CURVE-FITTING METHODS AND THE MESSAGES THEY SEND